

# Model Matematika Numerik

## Difusi Numeris

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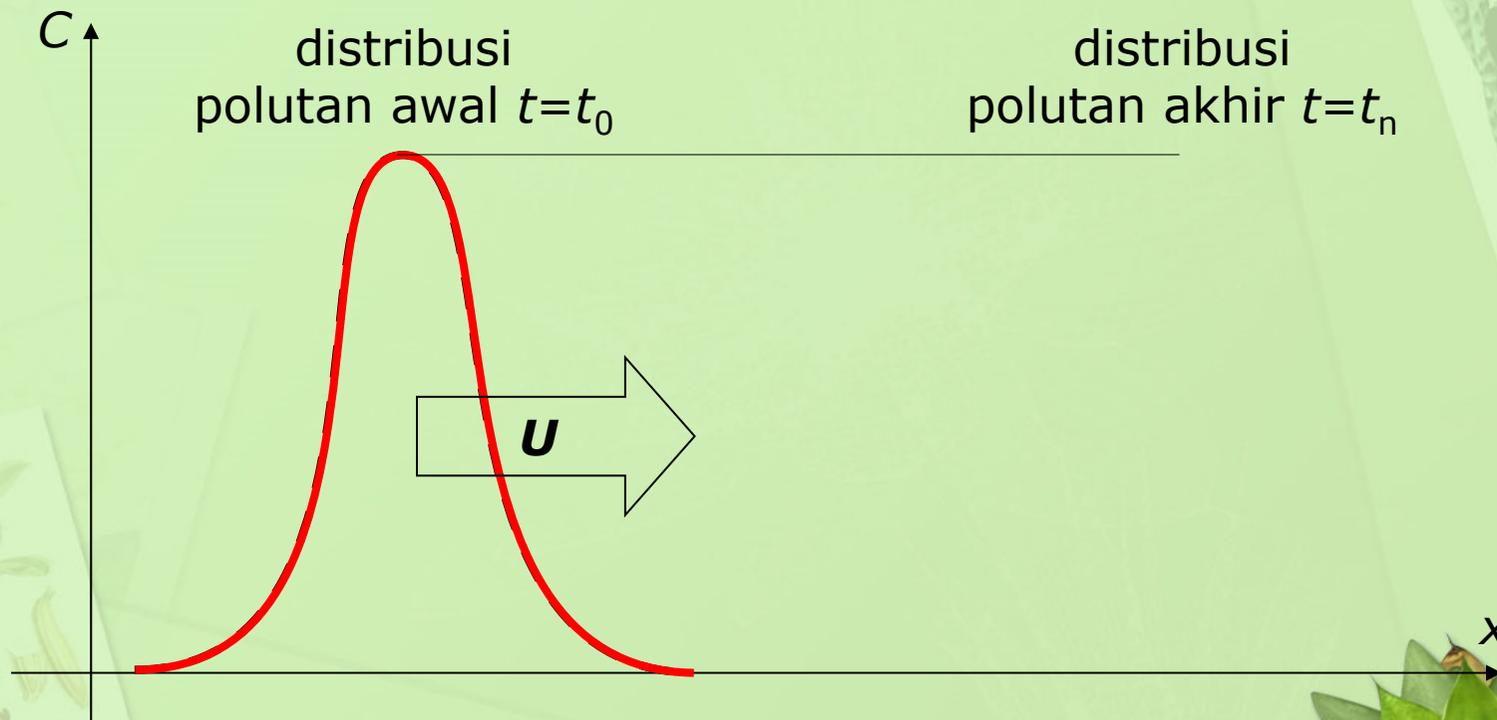
# Persamaan Dasar

- Persamaan Adveksi Murni

$$\frac{\partial C}{\partial t} + U \frac{\partial C}{\partial x} = 0$$

- $C$ , konsentrasi polutan  
 $U$ , kecepatan aliran  
 $t$ , waktu  
 $x$ , ruang, lokasi

# Interpretasi Persamaan Adveksi



Karena adveksi murni, maka distribusi polutan hanya bergerak karena pengaruh kecepatan aliran sebesar  $U$ , sedangkan bentuk distribusi konsentrasinya harus tetap.

# Penyelesaian Karakteristik Linier

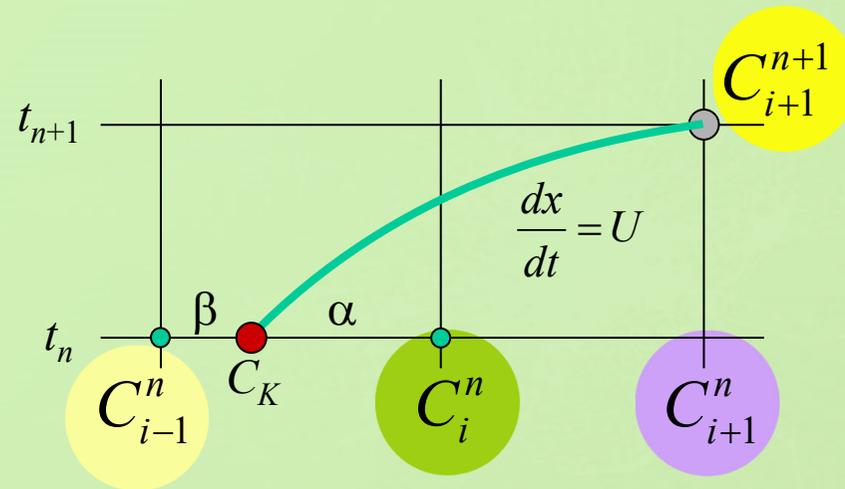
- Dengan metoda karakteristik dengan interpolasi linier diperoleh

$$C_{i+1}^{n+1} = \frac{\alpha}{\Delta x} C_{i-1}^n + \frac{\Delta x - \alpha}{\Delta x} C_i^n$$

akan diselidiki apakah formulasi diatas benar-benar merupakan penyelesaian persamaan adveksi murni:

$$\frac{\partial C}{\partial t} + U \frac{\partial C}{\partial x} = 0$$

# Gunakan deret Taylor



- Ekspansikan semua parameter di atas:

$$C_{i-1}^n$$

$$C_i^n$$

$$C_{i+1}^{n+1}$$

ke parameter

$$C_{i+1}^n$$

# Deret Taylor

$$C_{i+1}^{n+1} \approx C_{i+1}^n + \frac{\partial C}{\partial t} \Delta t + \frac{\partial^2 C}{\partial t^2} \frac{\Delta t^2}{2}$$

$$C_i^n \approx C_{i+1}^n - \frac{\partial C}{\partial x} \Delta x + \frac{\partial^2 C}{\partial x^2} \frac{\Delta x^2}{2}$$

$$C_{i-1}^n \approx C_{i+1}^n - \frac{\partial C}{\partial x} 2\Delta x + \frac{\partial^2 C}{\partial x^2} 2\Delta x^2$$

- Faktor turunan kedua dari C terhadap  $t$  dijelaskan pada slide berikut.

# Manipulasi Pers. Dasar

- Pers. Dasar diubah menjadi

$$\frac{\partial C}{\partial t} + U \frac{\partial C}{\partial x} = 0 \Rightarrow \frac{\partial C}{\partial t} = -U \frac{\partial C}{\partial x}$$

$$\frac{\partial^2 C}{\partial t^2} = \frac{\partial}{\partial t} \left( -U \frac{\partial C}{\partial x} \right) \Rightarrow \frac{\partial^2 C}{\partial t^2} = -U \frac{\partial}{\partial t} \left( \frac{\partial C}{\partial x} \right)$$

- Jadi

$$\frac{\partial^2 C}{\partial t^2} = -U \frac{\partial}{\partial x} \left( \frac{\partial C}{\partial t} \right) \Rightarrow \frac{\partial^2 C}{\partial t^2} = -U \frac{\partial}{\partial x} \left( -U \frac{\partial C}{\partial x} \right)$$

$$\frac{\partial^2 C}{\partial t^2} = U^2 \frac{\partial^2 C}{\partial x^2}$$

# Diperoleh korelasi

$$C_{i+1}^{n+1} \approx C_{i+1}^n + \frac{\partial C}{\partial t} \Delta t + U^2 \frac{\partial^2 C}{\partial x^2} \frac{\Delta t^2}{2}$$

$$C_i^n \approx C_{i+1}^n - \frac{\partial C}{\partial x} \Delta x + \frac{\partial^2 C}{\partial x^2} \frac{\Delta x^2}{2}$$

$$C_{i-1}^n \approx C_{i+1}^n - \frac{\partial C}{\partial x} 2\Delta x + \frac{\partial^2 C}{\partial x^2} 2\Delta x^2$$

# ... manipulasi lanjut ... 1

$$C_{i+1}^{n+1} = \frac{\alpha}{\Delta x} C_{i-1}^n + \frac{\Delta x - \alpha}{\Delta x} C_i^n$$

dengan

$$C_{i+1}^{n+1} \approx C_{i+1}^n + \frac{\partial C}{\partial t} \Delta t + U^2 \frac{\partial^2 C}{\partial x^2} \frac{\Delta t^2}{2}$$

$$\left(1 - \frac{\alpha}{\Delta x}\right) C_i^n \approx \left(1 - \frac{\alpha}{\Delta x}\right) C_{i+1}^n - \left(1 - \frac{\alpha}{\Delta x}\right) \frac{\partial C}{\partial x} \Delta x + \left(1 - \frac{\alpha}{\Delta x}\right) \frac{\partial^2 C}{\partial x^2} \frac{\Delta x^2}{2}$$

$$\frac{\alpha}{\Delta x} C_{i-1}^n \approx \frac{\alpha}{\Delta x} C_{i+1}^n - \frac{\alpha}{\Delta x} \frac{\partial C}{\partial x} 2\Delta x + \frac{\alpha}{\Delta x} \frac{\partial^2 C}{\partial x^2} 2\Delta x^2$$

## ... manipulasi lanjut ... 2

$$\frac{\partial C}{\partial t} \Delta t + U^2 \frac{\partial^2 C}{\partial x^2} \frac{\Delta t^2}{2} = -\left(1 + \frac{\alpha}{\Delta x}\right) \frac{\partial C}{\partial x} \Delta x + \left(1 + 3 \frac{\alpha}{\Delta x}\right) \frac{\partial^2 C}{\partial x^2} \frac{\Delta x^2}{2}$$

$$\frac{\partial C}{\partial t} \Delta t + \left(1 + \frac{\alpha}{\Delta x}\right) \frac{\partial C}{\partial x} \Delta x = \left(1 + 3 \frac{\alpha}{\Delta x}\right) \frac{\partial^2 C}{\partial x^2} \frac{\Delta x^2}{2} - U^2 \frac{\partial^2 C}{\partial x^2} \frac{\Delta t^2}{2}$$

$$\frac{\partial C}{\partial t} \Delta t + (\Delta x + \alpha) \frac{\partial C}{\partial x} = \left(1 + 3 \frac{\alpha}{\Delta x}\right) \frac{\partial^2 C}{\partial x^2} \frac{\Delta x^2}{2} - U^2 \frac{\partial^2 C}{\partial x^2} \frac{\Delta t^2}{2}$$

$$\left(\frac{\partial C}{\partial t} + \frac{\Delta x + \alpha}{\Delta t} \frac{\partial C}{\partial x}\right) \Delta t = \left(1 + 3 \frac{\alpha}{\Delta x}\right) \frac{\partial^2 C}{\partial x^2} \frac{\Delta x^2}{2} - U^2 \frac{\partial^2 C}{\partial x^2} \frac{\Delta t^2}{2}$$

# ... manipulasi lanjut ... 3

substitusi (lihat gambar di depan):  $U\Delta t = \Delta x + \alpha$

$$\left(\frac{\partial C}{\partial t} + U \frac{\partial C}{\partial x}\right) \Delta t = (1 + 3 \frac{\alpha}{\Delta x}) \frac{\partial^2 C}{\partial x^2} \frac{\Delta x^2}{2} - \frac{\partial^2 C}{\partial x^2} \frac{\Delta x^2 + 2\alpha\Delta x + \alpha^2}{2}$$

$$\left(\frac{\partial C}{\partial t} + U \frac{\partial C}{\partial x}\right) \Delta t = (1 + 3 \frac{\alpha}{\Delta x}) \frac{\partial^2 C}{\partial x^2} \frac{\Delta x^2}{2} - \frac{\partial^2 C}{\partial x^2} \frac{\Delta x^2 + 2\alpha\Delta x + \alpha^2}{2}$$

$$\left(\frac{\partial C}{\partial t} + U \frac{\partial C}{\partial x}\right) \Delta t = \frac{\cancel{\Delta x}}{2} \frac{\cancel{\partial^2 C}}{\partial x^2} + \frac{3}{2} \alpha \Delta x \frac{\partial^2 C}{\partial x^2} - \frac{\cancel{\Delta x^2}}{2} \frac{\cancel{\partial^2 C}}{\partial x^2} - \alpha \Delta x \frac{\partial^2 C}{\partial x^2} - \frac{\alpha^2}{2} \frac{\partial^2 C}{\partial x^2}$$

$$\frac{\partial C}{\partial t} + U \frac{\partial C}{\partial x} = \alpha \left( \frac{\Delta x - \alpha}{2\Delta t} \right) \frac{\partial^2 C}{\partial x^2}$$

# ... manipulasi lanjut ... 4

Definisi:  $Cr = \frac{U \Delta t}{\Delta x}$      $U \Delta t = \Delta x + \alpha$

$$\alpha = U \Delta t - \Delta x = Cr \Delta x - \Delta x = (Cr - 1) \Delta x$$

$$\frac{\partial C}{\partial t} + U \frac{\partial C}{\partial x} = \alpha \left( \frac{\Delta x - \alpha}{2 \Delta t} \right) \frac{\partial^2 C}{\partial x^2}$$

$$\frac{\partial C}{\partial t} + U \frac{\partial C}{\partial x} = \frac{\Delta x^2}{2 \Delta t} (Cr - 1)(2 - Cr) \frac{\partial^2 C}{\partial x^2}$$

# ... manipulasi lanjut ... 5

Definisi lebih umum:  $Cr = \frac{U\Delta t}{\Delta x}$      $U\Delta t = k\Delta x + \alpha$

$$\alpha = U\Delta t - k\Delta x = Cr\Delta x - k\Delta x = (Cr - k)\Delta x$$

$$\frac{\partial C}{\partial t} + U \frac{\partial C}{\partial x} = \alpha \left( \frac{\Delta x - \alpha}{2\Delta t} \right) \frac{\partial^2 C}{\partial x^2}$$

$$\frac{\partial C}{\partial t} + U \frac{\partial C}{\partial x} = \underbrace{(Cr - k)(1 - Cr + k)}_{K_n} \frac{\Delta x^2}{2\Delta t} \frac{\partial^2 C}{\partial x^2}$$

$$\frac{\partial C}{\partial t} + U \frac{\partial C}{\partial x} = K_n \frac{\partial^2 C}{\partial x^2}$$

# Persamaan Dasar Berubah

- Dengan metoda karakteristik (linier) ini persamaan berubah menjadi

$$\frac{\partial C}{\partial t} + U \frac{\partial C}{\partial x} = K_n \frac{\partial^2 C}{\partial x^2}$$

$K_n$  disebut difusi numeris, karena koefisien tersebut merupakan *side-effect* dari teknik numerik yang dipilih.

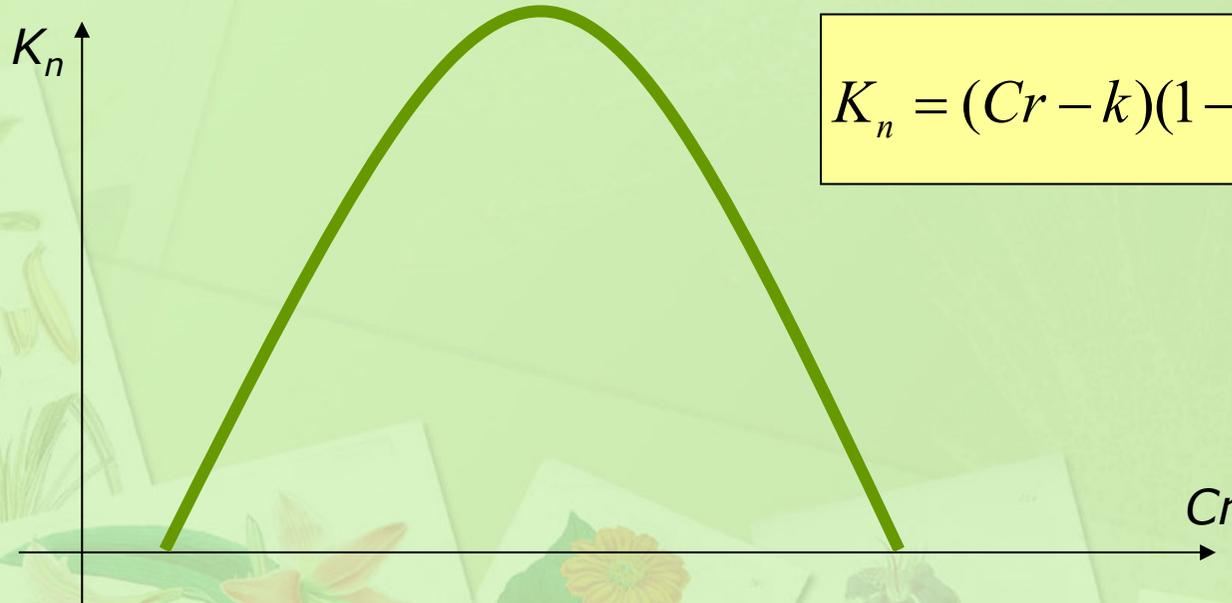
# Koefisien Difusi Numeris

- Koefisien Difusi Numeris,  $K_n$  merupakan fungsi dari bilangan Courant:

$$Cr = \frac{U\Delta t}{\Delta x}$$

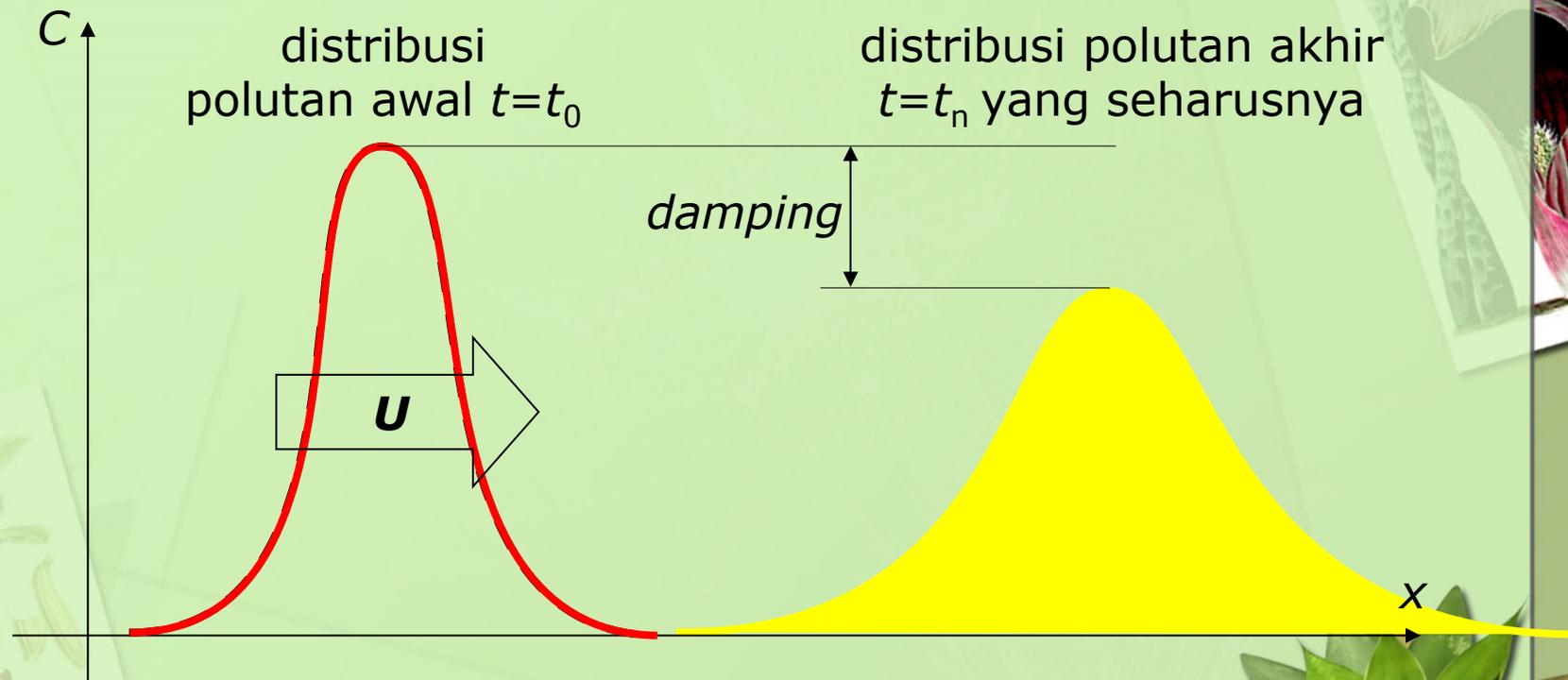
# $K_n$ versus $Cr$

- Contoh kasus korelasi antara  $K_n$  versus  $Cr$
- $K_n$  membesar maka penyelesaiannya mengalami *damping* makin besar.



$$K_n = (Cr - k)(1 - Cr + k) \frac{\Delta x^2}{2\Delta t}$$

# Difusi Numerik vs *Damping*



Karena Difusi Numeris,  $K_n$ , maka distribusi polutan tidak hanya bergerak karena pengaruh kecepatan aliran sebesar  $U$ , namun mengalami dispersi semu karena teknik numerik yang digunakan.

# Skema-skema lain

- Untuk skema-skema beda hingga yang lain misalkan skema maju dan skema mundur dapat dilakukan hal yang sama dan dapat diperoleh sifat difusi numerisnya.
- Demikian pula untuk persamaan dasar yang lainnya dapat diperoleh karakteristik penyelesaian numeriknya terhadap skema yang digunakan.